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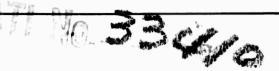
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NATIONAL ADVISORY COMMITTEE FOR AERONAUTICS

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FLIGHT TESTS OF THE SIKORSKY HNS-1 (ARMY YR-4B) HELICOPTER

I - EXPERIMENTAL DATA ON LEVEL-FLIGHT PERFORMANCE

WITH ORIGINAL ROTOR BLADES

By F. B. Gustafson

Langley Memorial Aeronautical Laboratory
Langley Field, Va.



WASHINGTON

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NATIONAL ADVISORY COMMITTEE FOR AERONAUTICS

MENORANDUM REFORT

for the

Army Air Forces, Air Technical Service Command

and the

Bureau of Aeronautics, Navy Department
FLIGHT TESTS OF THE STEORSKY BNS-1 (ARMY YR-4B) HELICOPTER

T - EXPERIMENTAL DATA ON LEVEL-FLIGHT PERFORMANCE

WITH ORIGINAL BOTOR BLADES

By F. B. Gustefson

SUMMARY

Results of performance measurements made in level flight with the HNS-1 (Army YR-4R) belicopter are presented. These data include torquemeter measurements of shaft power for both the main rotor and the tail rotor. The power data, in conjunction with full-scale-tunnel data on the lift and drag of the fuselage, are used to calculate the drag-lift ratio for the main rotor.

The following results were obtained for the HMS-1 helicopter, as tested at a gross weight of approximately 2560 counds and equipped with the original set of mainrotor blades: minimum main-rotor-shaft power at cruising rpm, approximately 99 horsepower at a speed of 40 miles per hour; rotor-shaft power absorbed by tail rotor at cruising rpm, approximately 3 to h horsepower over a range of speeds from 25 to 80 miles per hour; maximum ratio of lift to drag for the main rotor attainable within the available speed range, 6.7; maximum value of weightdrag ratio (ratio of weight to the drag equivalent to the total rotor-shaft power), 3.5; speed for maximum weight-drag ratio, approximately 67 miles per hour. The results also indicate that main-rotor-shaft power required is appreciably affected by rctor rpm, a reduction in rpm of 5 percent corresponding to a reduction of approximately 3 to 1: horsepower when operating at or near the speed for minimum power.

INTRODUCTION

In order to provide data with which theory and wind-tunnel measurements on powered rotating-airfoil systems may be checked, flight tests are being conducted at Langley Laboratory with a Sikorsky HNS-1 (Army YE-12) helicopter. These tests include performance measurements in level flight, hovering, and glides and climbs, and camera observations of blade motion in selected conditions. This report presents the results of the level-flight performance measurements that were made with the original set of main-rotor blades.

SYMBOLS

 V_c calibrated sirspeed (indicated airspeed corrected for instrument and installation errors; can be considered equal to $V\left(\frac{\rho}{\epsilon_0}\right)^{1/2}$ in the present case)

V true alrapsed

F mass density of air

conditions (0.002578 slug per foot)

9 average main rotor-blade pitch, uncorrected for play in linkage and for mean blade twist

 μ tip-speed ratio $\left(\frac{V\cos\alpha}{QR}\right)$

a spindle angle of an equivalent rotor with no periodic variation of the rotor-blade pitch angle, measured in the plane of symmetry and referenced to a line perpendicular to the flight path; positive aft

solidity $\frac{bc_e}{\pi R}$ where $c_e = equivalent chord = <math>\frac{\int_0^R cr^2 dr}{\int_0^R r^2 dr}$

giving $\sigma = 0.060$ for the present case

- b number of blades
- a slope of lift coefficient against section angle of attack (radian measure), assumed equal to 5.73 in this report
- Op newer coefficient (Rotor-shaft power input)
- P/L shaft-power parameter. The symbol P is equal to the rotor-shaft power divided by the volocity along the flight path. It is, therafore, also equal to the drag force that could be overcome by the shaft power at the flight velocity
- ar fuselage angle of attack (angle between relative wind and a line in the plane of symmetry and parpendicular to the main rotor-shaft axis; nositive when nose up)
- Δα_f correction to fuselage angle of attach to allow for rotor downwash
- $\alpha_{\mathbf{f_c}}$ corrected tuselage angle of attack ($\alpha_{\mathbf{f}} + \Delta \alpha_{\mathbf{f}}$)
- AUL correction to rotor lift coefficient for fuselage download
- G_L rotor lift coefficient (G_{Luncor} + AG_I)
- G_{m} thrust coefficient $\left(\frac{\text{corrected rotor lift}}{\rho\Omega^2 \pi R^4}\right)$
- $\left(\frac{D}{L}\right)_{pf}$ parasite drag of fuselage, rotor head, and blade shanks, divided by corrected main-rotor lift

Ω

$\left(\frac{\mathrm{D}}{\mathrm{L}}\right)_{\mathrm{pt}}$	parasite-drag contribution of teil rotor divided by corrected main-rotor lift
$\left(\frac{\mathbf{D}}{\mathbf{L}}\right)_{\mathbf{r}}$	drag-lift ratio of main rotor after applying corrections for fuselage download and for fuselage and auxiliary rotor paresite drag
$\mathbf{c_{L_f}}$	fuselege lift coefficient $\left(\frac{\text{Fuselage lift}}{\frac{1}{2}\rho V^2 \pi R^2}\right)$
$\mathtt{c}_{\mathtt{D}_{\mathbf{f}}}$	fuselage drag coefficient $\left(\frac{\text{Fuselage drag}}{\frac{1}{2}\rho V^2 \pi R^2}\right)$
R	rotor-blade radius
r	radius of blade alement

APPARATUS

rotor angular velocity, radians per second

corrected rotor lift

Description of aircraft. - General views of the HNS-1 helicopter (AAF Serial No. 43-28229) are shown in figures 1, 2, and 3. The plan form of the main- and tail-rotor blades is shown in figure 4. Dimensions and other details for the aircraft as flown are as follows:

General characteristics:	
Gross weight as flown (±2 percent), lb	2560
Disk loading, lb/sq ft	2.26
Power loading as flown (normal rated power),	
1b/bhp	14.2
Parasite drag area D/q, typical flight	
condition, sq ft	
Power rating for take-off 190 bhp at 2250	rpm
Power rating, normal 180 bhp at 2100	rpm
Gear ratio, engine to main rotor 9.	
Gear ratio, engine to tail rotor	0:17
Fuel capacity, gals	30
Center-of-gravity position, below plane	
of flapping hinges, feet	4.5

Main-rotor characteristics.	
Redius, ft	
TABLE AND	
Alada twist None	
Selidity, $\frac{-e}{}$	1
πR	
Hlade area (total. three blades), so ft 65.5)
Plade section NACA 0012	
Plade section	
Coalie witch werde chtained from	
Lorgitudinal stick rotion, deg 16	;
Lateral stick motion, deg	,
Direction of rotation: counterclockwise as viewed from	m
abova	
Moment of inertia of blode about flapping axis,	
slug ft ² · · · · · · · · · · · · · · · · · · ·	5
slug ft	,
Blade center of gravity, from & of rotor shaft, in. 94.3	,
Brag hinge location, from & of rotor shaft, in 9.08	}
Flanging hinge & location, from & of rotor	
,	
shaft in)
shaft, in)
,)
Tail-rotor characteristics:	
Tail-rotor characteristics:	
Tail-rotor characteristics: Radius, ft	á
Tail-rotor characteristics: Radius, ft	á
Tail-rotor characteristics: Redius, ft	3 Ο
Tail-rotor characteristics: Redius, ft	Θ
Tail-rotor characteristics: Redius, ft	Θ
Tail-rotor characteristics: Radius, ft	Θ
Tail-rotor characteristics: Redius, ft	Θ
Tail-rotor characteristics: Radius, ft	Θ
Tail-rotor characteristics: Redius, ft	5 2 2 2 6
Tail-rotor characteristics: Radius, ft	5 2 2 2 6

Instrumentation and methods. - Quantities measured during the forward-flight tests included the following:

Ai rspeed Fotor rpm Engine manifold pressure Attitude angle (shaft Main-rotor-shaft torque Tail-rotor-shaft torque Free-air temporature Intake-air temperature Free-air static pressure

Main-rotor pitch Tail-rotor pitch inclination) Upwash and yaw flow angles ahead of the rotor disk Cyclic pitch control position The free-sir temperature and the engine intake-sir temperature were obtained from indicating instruments; all other quantities were obtained from NACA recording instruments.

The airspeed was determined by means of a double-swiveling pitot-static installation (fig. 5) having its static holes located at a point 25% inches ahead of the main-roter shaft and 5¼ inches below the plane of the flapping hinges. The installation was calibrated by means of a trailing-pitot-static bomb suspended approximately 100 feet below the roter. The calibration data are shown in figure 6.

The engine manifold pressure, intake-air temperature, and rpm values were used to calculate engine brake horsepower by use of the calibration curve given in Technical Order AN Ol-10 DA-1.

The main- and tail-rotor-shaft torques were obtained by means of strain-gage torquemeters. The strainsensitive elements for the main rotor were mounted on the driveshaft between the gear box and the pylon thrust bearing. Those for the tail rotor were mounted on that portion of the driveshaft between the tail-rotor gear box and the rearmost shaft bearing.

The torquemeter shaft assemblies, including the strain-sensitive elements and sliprings, were designed by Baldwin-Southwark Division of the Baldwin Locomotive Works under contract with the Army Air Forces. An NACA recording galvanometer was used to measure the gage output. Voltage control and also a periodic check throughout each run on the zero reading and sensitivity of the galvanometer circuit were obtained with additional equipment developed especially for the purpose.

The values of main-rotor pitch setting and control-stick (cyclic pitch) position were obtained from control-position recorders attached to the push-pull tubes extending from inside the fuselage to the rotor head. The stick position is referred to the position for zero cyclic pitch variation. The available stick travel from this position as measured at the top of the stick is 6.3 inches forward, 7.1 inches aft, h.1 inches right, and 7.6 inches left. The amplitude of the cyclic pitch variation, in degrees from the mean pitch value, may be estimated by multiplying the stick displacement in inches by 1.25.

The phase angle of the cyclic pitch action, in degrees from the rearmost position of the blade, may be estimated for the power-on condition by assuming that the maximum effect of the longitudinal stick deflection occurs at 55° and at 245° azimuth and that the maximum effect of the lateral stick displacement occurs at 155° and 335° azimuth. These estimates must be viewed as approximate, however, because of linkage play, periodic blade twist, and the change in the phase of the control action with changes in rotor torque or rpm.

The values for the tail-rotor pitch were obtained from a control-position recorder attached to the tail-rotor control cables. This installation was calibrated with a small pitch decreasing moment applied to the blades, to insure that the play in the system (roughly ±1° from the rean position) would be taken up in a direction corresponding to that anticipated for the flight conditions covered.

The attitude angle (main-rotor-shaft inclination from the vertical, positive rearward) was determined by means of a pendulum inclinameter.

The yaw and the upwash flow angles were obtained by means of a calibrated yaw head mounted on the end of the airspeed boom (fig. 4). These tubes were located 250 inches ahead of the rotor shaft and 54 inches below the plane of the flapping hinges. The angles given are referred to a line in the plane of symmetry and perpendicular to the rotor shaft. A positive yaw angle corresponds to right yaw or left sideslip.

REDUCTION OF DATA

The method of calculation of the majority of the coefficients presented will be appearent by definition. The methods of obtaining tip-speed ratio μ and rotor drag-lift ratio D/L, however, require some explanation.

Tip-speed ratio μ . Evaluation of the cos α term in the accepted definition of the tip-speed ratio $\mu = \frac{V \cos \alpha}{\Omega E}$ requires the determination of an equivalent spindle angle for a rotor with no periodic variation of the rotor-blade pitch angle. This equivalent angle was

determined by adding the amplitude of the longitudinal component of the rotor-blade cyclic pitch variation (periodic blade pitch angle change about transverse axis of ship) estimated from the stick-position data to the measured shaft angle.

Retor drag-lift ratio D/L. The evaluation of rotor drag-lift ratio requires a somewhat arbitrary division of the drag losses into fuselage parasite drag and rotor profile-drag losses. In this report the drag of the hub structure and the cylindrical blade shanks has been charged to fuselage parasite loss. This division is convenient because the drag of these items varies with forward speed rather than with rotational speed. It also gives a more correct index of the performance to be expected from later rotor designs, inasmuch as the relative drag of the hub structure on the ENS-l is obviously much greater than that on any of the rore recent designs.

In determining the drag-lift ratios of the main rotor from measured values of shaft power and known values of gross weight, allowances have been made for the following factors:

- (1) Power required to overcome the parasite drag of the fuselege, rotor head, and blade shanks.
- (2) Fower required to overcome the drag force on the tail rotor. (This power is totally independent of the power transmitted through the tail rotor shaft.)
- (3) Rotor lift, in excess of the gross weight, required because of the downward air load on the fuselage.

The individual values for all of these allowances have been included in table II in order that their magnitude may be noted.

Items (1) and (3) were determined by use of unpublished full-scale-tunnel data on the lift and drag of the fuselage of a YR-4B helicopter (AAF Serial No. 43-28225). These data were obtained with the airspeed boom shown in figure 5 mounted on the YR-4B fuselage, in order to make the data directly applicable to the flight tests. The measured drag coefficients were increased by 0.00035, or about 2 percent, as an allowance for the drag of the

cylindrical blade shanks; this increment was estimated from data on yawed cylinders. The fuselage drag and lift curves used in the analysis are shown in figure 7. The wind-tunnel values were obtained over a range of angles of attack but the fuselage was, of course, not being subjected to the downwash from the retor. As an approximate allowance for this downwash, the fuselage angle of attack for the flight conditions was taken as equal to the measured angle minus $57.3~(\text{C}_{\text{L}}/4)$ which term represents the approximate induced flow angle at the retor.

No directly applicable data were available for evaluation of item (2). As a rational approximation, theoretical calculations similar in principle to those of the example of reference 1 were made. The process consisted in finding an airfoil-section profile-drag value which results in a calculated value of shaft power equal to the measured value. The same profiledrag value was then used to calculate the power required to pull the tail rotor. The maximum value so obtained was 3.4 horsepower; this value corresponds to maximum speed. In terms of equivalent drag area, the parasite drag allowance for the tail rotor was nearly constant, varying only from 0.8 to 1.0 square foot over the entire range of combinations of rpm and speed. The mean bladesection drag coefficient required to make the calculated tail-rotor-shaft power equal the measured shaft power varied from 0.010 to 0.015.

It will be noted that the main-rotor thrust coefficients presented are based on the assumption that rotor thrust equals rotor lift. This assumption is justified by the fact that refinement of the thrust value by inclusion of the drag component would result in a maximum difference of about 1 percent.

RESULTS

The test data corrected for instrument errors are presented in table I. The values of the main-rotor drag-lift ratio and other parameters derived from those data are given in table II.

The power-required data for the main rotor obtained from the torquemeter are plotted against true airspeed in figure 3. Because the deviations in weight and density ratio were small, no corrections have been applied for variations of these factors from their mean values in preparing the horsepower-velocity plot. A check of the error involved indicated that the maximum correction which would be applied to an individual value for horsepower, in converting to average conditions, would be less than 2 percent. In calculating dimensionless quantities, however, individual values of weight and density were employed for each test point. The data of figure 3 have been replotted in coefficient form in figure 9. The main-rotor drag-lift ratios, obtained from the power data as already described, are shown in figure 10.

The data in figures 3, 9, and 10 have been grouped according to the values of the nondimensional thrust coefficient C_T . From an operational standpoint, the thrust coefficient is most readily changed by varying the rpm of the engine and hence of the rotor, and for this reason a value of engine rpm corresponding to each value of C_T is given. For this purpose the average of the actual C_T values within each group has been used. The conversion from C_T to rpm is based on everage values of weight and density and an average download allowance; as already mentioned, however, the variations in weight and density are not large enough to be significant in this connection, and examination of table II will show that the download variation is likewise small.

No data were taken at speeds below approximately 30 miles our hour because of the difficulty which the pilot experienced in maintaining steady conditions at speeds between approximately 30 miles per hour and near-hovering speeds.

DISCUSSION

Main-rotor power. - Interpolation of the data presented in figure 8 indicates a minimum value of main-rotor-shaft horsepower of approximately 99 horsepower for cruising rpm (2100 engine rpm, 225 rotor rpm) at a speed of approximately 40 miles per hour. A reduction of power required of about 3 to 4 horsepower for every 5-percent reduction in rotor rpm is also indicated over

most of the speed range, including the speed for minimum power. This reduction in power required at a given speed may be attributed to the combined benefits of operating at higher pitch angles and higher tip-speed ratios while retaining fixed values of parasite and induced losses. This same trend toward lower power with lower rpm may be shown with the data in nondimensional form by plotting P/L against C_L , since the parasite and induced losses are fixed by the lift coefficient. The form of the resulting curves is believed to be more suitable for study, however, if the velocity parameter $1/\sqrt{C_L}$ is used; such a plot is shown in figure 11. The ratio $1/\sqrt{C_L}$ is approximately equal to the ratio of the actual velocity of flight to that for a lift coefficient of unity; the relation would be exact if C_L were based on weight instead of the rotor lift, which includes a varying percentage allowance for fuselage download.

Examination of figure 9 indicates that minimum F/L and hence maximum range will be obtained at a tip-speed ratio of approximately 0.22, which corresponds to a speed of 67 miles per hour at cruising rpm. The minimum value of P/L at cruising rpm,0.265, corresponds to an equivalent lift-drag ratio of 3.8. If the lift allowance made for the fuselage download is removed and an allowance made for the power absorbed through the tail-rotor shaft, an equivalent weight-drag ratio of 3.5 is obtained for the aircraft. The values of minimum P/L for the various thrust coefficients (see faired curves of fig. 11) show relatively little effect of rotational speed; in particular, the reduction in P/L obtained by using rotational speeds below that for cruising is small. The ratios just given for the cruising condition, therefore, are considered to be reasonably representative of the performance of the aircraft as tested.

The minimum value of main rotor D/L (fig. 10) is 0.15, corresponding to an L/D of 6.7. This value was obtained from data taken with wide-open throttle. Inspection of the data of figure 10 indicates that appreciably higher rotor L/D values might be expected if higher tip-speed ratios could be reached. The extension of the tip-speed ratio values by use of lower rotational speed, however, was carried to the lowest rotational speed at which the pilot could control the aircraft. Calculations indicate that tip stalling should set in at approximately this same combination of thrust coefficient and tip-speed ratio values; consequently,

further increase in tip-speed ratio and L/D would have to be obtained by an increase in forward speed rather than by reduction of rotational speed.

Tail-rotor-shaft power. Inspection of the values of the tail-rotor power given in table I will indicate that for speeds between 25 and 80 miles per hour the tail rotor absorbs from 3 to 4 shaft horsepower at normal rpm. These data are shown plotted against velocity, with the data points grouped according to main-rotor thrust coefficient, in figure 12. Some effect of speed is evident, the tendency being a decrease in shaft power with increase in speed. There are also indications of an effect of tail-rotor rpm on shaft power; this effect is most consistently evidenced in the top-speed data (70 to 30 miles per hour, flight 9), which data indicate a reduction from about 3.5 horsepower to about 2 horsepower as the engine rpm is reduced from 2250 to 1940.

Analysis indicates that the shaft power absorbed by the tail rotor will vary with the yaw angle of the helicopter. To evaluate this effect a continuous record was taken at 70 miles per hour with the yaw angle slowly increased and decreased through a range of ±15°. A change of one horsepower in the tail-rotor-shaft power for every 3.5° yaw was indicated, the lower shaft power corresponding to right yaw or left sideslip. Inspection of the yaw angle values given in table I in the light of this relation indicates that the maximum error in tail-rotor-shaft power, resulting from yaw of the aircraft, is approximately 0.5 horsepower.

The power absorbed by the drag of the tail rotor has already been discussed in the section entitled Reduction of Data.

CONCLUSIONS

The level-flight performance data obtained on the HNS-1 helicopter, as tested at a gross weight of approximately 2560 pounds and equipped with the original set of main-rotor blades, indicates the following conclusions.

1. The minimum shaft power required by the main rotor at cruising rpm (225 rotor rpm, 2100 engine rpm) was approximately 99 horsepower at a speed of 40 miles per hour.

- 2. The shaft power absorbed by the tail rotor at cruising ron was approximately 3 to 4 horsepower over a range of speeds from 25 to 80 miles per hour.
- 3. A reduction of 5 percent in rotor rpm results in a reduction of approximately 3 to 4 horsepower in the value of main-rotor-shaft power, at or near the speed for minimum power.
- 4. The maximum lift-drag ratio for the main rotor was approximately 6.7. A higher L/D could probably be obtained if higher speeds could be reached.
- 5. A maximum value of weight-drag ratio (ratio of weight to the drag equivalent of the total rotor-shaft power) of 3.5 was obtained at a speed of approximately 57 miles per hour.

Langley Hemorial Advisory Committee for Aeronautics
Langley Field, Va.

REFERENCE

1. Bailey, F. J., Jr., and Gustafson, F. B.: Charts for Fstimation of the Characteristics of a Helicopter Fotor in Forward Flight. I - Profile Drag-Lift Ratio for Untwisted Rectangular Blades. NACA ACR No. 14507, 1944.

TABLE I

NATIONAL ADVISORY COMMITTEE FOR AERONAUTICS

LEVEL PLICHT DATA SURGARY

		T	Flight Bo	4			6730	*					
Fun no.	7	8		4	80		4	•		9		ឌ	ង
Calibrated airspeed (mph) Density ratio, ρ/ρ_0 True speed (mph)	65.6 .913 68.6	60.6 .915 63.3		5.6.7 816.1	37.3 38.8		35.2 85.2 8.2	.923 42.0		41.3 2015 43.1		.919 50.8	.920 50.8
Gross weight (1bs) Rotor rpm Engine rpm	8 8 8 8 8 8	25,27,20,20,20,20,20,20,20,20,20,20,20,20,20,		252 2070	223 223 20 60		22 22 28 22 23 28 23 23 28	25.73 20.20 20.20 20.20		2572 235 2390		236 238 2220	1863 1863 1863 1863 1863 1863 1863 1863
Atmos, pressure (in. Hg) Free air temp. $^{(OF)}$ Intake air temp. $^{(OF)}$	738.71	3.F I		73.38	8.E I		k 148	3 1 3 %		14%		138.5	8.E.1
1. Hg)	2.63 25 26 26 26 26 26 26 26 26 26 26 26 26 26	25.52 22.52	23.0 110	138 138 138 138	322	រុង វង្	22. 132 162	2,72 %	2 % 2 % 2 %	22.6 105 105	445 445	ÉRS ÉRS	នូងន
	181	1%.			25.5		1.2.2.	127		155		7 2 8	1%4
Yaw angle (deg) Shaft inclination (deg) c.g. (in. behind shaft)	4.6.3.	25°5°		4.6. 7.7.	197	375	344	94. 8.		51.4 e.	25° 0.	9.6.	
	5.6 4.3	81.4 6.8.4 ,	-3.8 1.9 3.4	777	1.3		2.9 3.5	-1.2 1.6 3.2		-2.5 3.0		-2.1 1.1 2.8	3,27

TABLE I (cont.) LEVEL FLIGHT DATA SUMMARY

NATIONAL ADVISORY COMMITTEE FOR AERONAUTICS

28.15 1.25 8228 45.55 50.55 50.55 828 1 444 3.4 8.3 0.3 25.15 72.15 1.61 8.2 8.3 8 1 1 1 1 2.03.1 28.26 8.9% 5.0% **8228** 28.29 3.53 EZZ Z SES 3.4 28.28 28.28 28.28 28.28 28.28 RKS 7/5/11 28.33 2576 z K 28,33 69 :-45.0 .930 46.7 85.38 88 88 88 88 88 88 46.6 48.3 48.3 ម្ពុជម្ព 8. X 25.53 25.53 25.53 45.1 .927 46.8 EK'S 4.6 Flicht Io. 28.23 69 8228 8228 **883** 238 res 44. 8.10 Manifold pressure (in. Hg) Brake hp (power charts) Upwash at A.S. head (deg) Stick position (in. fwd.) Stick position (in. left) Calibrated airspeed (mph)
Density ratio, P/Po
True speed (mph) Atmos. pressure (in. Hg) Free sir temp. (OF) Yaw angle (deg) Shaft inclination (deg) c.g. (in. behind shaft) Hp, tail rotor (shaft) Pitch, main rotor (deg) Pitch, tail rotor (deg) Hp, main rotor (shaft) Intake air temp. (OF) Gross weight (1bs) Run no. Engine rpm Fotor rpm

TABLE E (cont.)

NATIONAL ADVISORY COMMITTEE FOR AERONAUTICS

LEVEL PLICHT DATA SURLARY

Flight No. 4 (sent.)

27	31.1 .911 32.6	2546 207 1930	22.32	* £ £	3.6 9.3 1.5	5077 7179	377
11	31.2 .914 32.6	87.78 7.78 7.78 7.78	86 : 8	ន្តអន្ត	3.7	11.0	2.7
4	31.1 .921 32.4	2552 237 2210	8 6 :	87.8 12.6	7.5	6644	227
23	31.2 .920 32.5	25.25 26.25	8.27 8.20	888 888	3.4 8.1 1.9	46.4	2.9
*	50.1 .919 52.2	22.23 200 200 200 200 200 200 200 200 200 2	8.15 1.15	823 4.43	25. 44. 1.	1.4.1. 1.8.0.1.	450
Run no.	Calibrated airspeed (mph) Density ratio, ρ/ρ_0 True speed (mph)	Gross weight (lbs) Rotor rpm Engine rpm	Atmos, pressure (in. Hg) Free air temp. $({}^{O}F)$ Intake air temp. $({}^{O}F)$	Manifold pressure (in. Hg) Brake hp (power charts) Hp, main rotor (shaft)	Hp, tail rotor (shaft) Pitch, main rotor (deg)	Yaw angle (deg) Shaft inclination (deg) c.g. (in. behind shaft)	Upwash at A.S. head (deg) Stick position (in. fwd.) Stick position (in. left)

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TARE I (cont.)

LEVEL PLICHT DATA SURVANT

			Flisht No. 5	. 5			7/2	7/25/14		
Run no.	-	~	•	4	8	9	80	6	9	
Calibrated airspeed (mph) Density ratio, ρ/ρ_0 True speed (mph)	7.5 216.	60.4 .915 63.1	.915 51.4	42.0 426. 43.9	32.2 .916 33.6	33.6 .919 35.0	36.4 38.0	51.4 .918 53.6	65.1 .916 68.0	
Gross weight (lbs) Fotor rpm Engine rpm	253	8833 8833	225	2527 225 2100	227 200 200 200 200 200 200 200 200 200	25.50 20.00	233 233 236 237 237 237 237 237 237 237 237 237 237	2515 225 220 220 220	2512 223 2030	
Atmos. pressure (in. Hg) Free air temp. ${}^{({}^{\circ}F)}$ Intake air temp. ${}^{({}^{\circ}F)}$	333 1	831 3	28.7 1.72	28.72 53.6 	88.65 83.0 1	88.1 5.64	8.8 8.6 8.0	8.3 8.9	28.7 24.6	
Manifold pressure (in. Hg) Brake hp (power charts) Hp, main rotor (shaft)	£83	25.03 25.03	322 8	428 428 4	ដូងដ	25.7 103 100	2 2 2 2 3 3 3	ន្តង្កង	25.8 136 130	
Hp, tail rotor (shaft) Fitch, main rotor (deg) Fitch, tail rotor (deg)	2.5 10.3	9.1	1221	4.2 8.1 .6	8.2	4.3	4.7 5.8	0.4. 7.4.	3.3	
Yaw angle (deg) Shaft inclination (deg) c.g. (in. behind shaft)		4:5- -5:2		6.5.	e: 1 e:	0.0 -1.0 8	0.6 -1.7 8	9,10	0.0	
Upwash at A.S. head (deg) Stick position (in. fwd.) Stick position (in. left)	-5.8 4.3	-4.0 1.8 3.5	3.0	-1.5 1.4 2.9	717	2.9	1.3 3.0	-4.0 1.5 3.2	3.9	

COMMITTEE FOR AERONAUTICS

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LEVEL PLICE DATA SURVANT

TABLE I (cont.)

LEVEL FLIGHT DATA SUMMARY

Plicht No. 9 (sont.)

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2,4 % 8 121 KKK 24.8 24.8 3gg 6.4 6.5 6.3 2228 3.2 10.2 0.8 2,68 2 ដ្ឋនិង្គិ EE's 2.3 8.8 8 282 282 282 282 នូងដ -2.1 -2.3 8.43 8.63 62.8 .940 64.7 2 2 2 3 3 3 S 0.4.4 2.8.4 6.60 78.5 100 68.3 2935 6.6 ន្តន្តន្តិ 428 2 0 & 4 4 24.8 100 100 100 68.6 .933 7.0 2222 428 83.83 80.03 8228 2.7 ZES. 484 82 83 80 83 8888 8888 2.7 4.6 28.83 E 33.93 £83, 3.2 6.0 4.5 222 .931 9.00 **88.**83 8 8 8 8 8 8 £23 557 577 577 2.5 8.6 0.9 4.2 Manifold pressure (in. Hg) Brake hp (power charts) Hp, main rotor (shaft) Upwash at A.S. head (deg) Stick position (in. fwd.) Stick position (in. left) Calibrated airspeed (mph) Density ratio, ρ/ρ_0 True speed (mph) Atmos. pressure (in. Hg) Free air temp. $\binom{5}{7}$ Hp, tail rotor (shaft) Pitch, main rotor (deg) Pitch, tail rotor (deg) Yaw angle (deg) Shaft inclination (deg) c.g. (in. behind shaft) Intake air temp. (OF) Gross weight (1bs) Run no. Engine rpm Rotor rpm

-										
(<u>1</u>)	0.177 196 .209	.236 .239 .436	3.85 2.85 2.85	rigini Livings	255 202 203	284 252	25. 25. 25. 25. 25.	ĕ¥.%	8224	398
) (1)	-000. -000. -000.	988	888	9888	888	988	988	982	9828	9828
$J^{d}\left(\frac{1}{\overline{a}}\right)$	0.086		035	5399		इंडेड	45.65		55.55	22.22
메니	0.267 272. 272.	25.00 25.00	3.5. 0.0. 0.0. 0.0. 0.0. 0.0. 0.0. 0.0.	2.0.2. v.	8,7,3 8,48	8,6,6,4 8,6,6,4	85.55 138.55	£. 55.55.	25.5. 15.8. 14.8.	83.7.7. 1.5.68
ભદ	4790.0 9580. 95.00.	0492 0426 0472	0491	05050 05050 05050 05168	0540 0482 0550	0500 0500 0486	1873 1773 1782 1782	2.2.2.2. 2.2.2.2.2.2.2.2.2.2.2.2.2.2.2.	0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.0	.0520 .0520 .0492
Ср × 103	0 50 50 50 50 50 50 50 50	24.25.25.25.25.25.25.25.25.25.25.25.25.25.	. 255 184 184	22. 22. 22. 21.2. 81.5. 81.5.	255 55 55 55 55	5,55 5,65 5,65 5,65 5,65 5,65 5,65 5,65	.297 1217 255	88.5	4555	. 306 . 306 . 301
5 8	0.0322	0316	.0327	.0278 .0321 .0270 .0337	.0272 .0314 .0349	.0272 .0307 .0304	.0356 .0268 .0310	.03761 .03363 .0363		.0269 .0342 .0356
ታ	0.0055 .0055 .0054	0000 47,000 47,700	200. 47.000. 47.000.	00.00 00	0000 0000 0000 0000	.0053 .0053	.0061 9460 659	90559	.0053 .0053 .0053	.0046 .0059
30	2.66 4.26 4.97	5.66 11.00 17.52	9.52	6.33 7.88 7.88 7.88 7.88 7.88 7.88	5.53	7.52	7.2 11.0 7.11	32.11	8.73 6.11 15.19	15.35
C.	0.221 .256 .298	1.051	1.411.556	22.5 23.5 27.5 27.9 27.9	2000	152	1220	425	425.	.9 26 .918 .928
TOP	400.0 400.0	988 488	200 200 200 200 200 200 200 200 200 200	8888	इंड ड	898	988	888 7.688	888	888 888
er.	6.00 G	-10.9	-9.7	9.66.6	9.46	686	9.11	-10.6	-13-09-7-09-8-13-8-0-7-13-8-13-13-13-13-13-13-13-13-13-13-13-13-13-	2077 7777 7777
Jog	1.5.4	464	-20.0	٠٠٠٠ منه: غ-غ	444	41.4	19.5	\$ 0.0 0.00	4.52	-13.2
(CL) uncor	0.216 .251 .294	1.043	1.399	.521 .578 .578 .578	292 282 384	333	. 459 . 701	619 667 669	519	.919 .911 .920
3.	0.224 .208 .190	173	833	135	188	4525	118	137	1500 1500 1500 1500 1500 1500 1500 1500	.100
6	10.1 9.6	8.50	280 140	1.81.0 v.v.s.	88 4.46.	9.6		888	8000 1041	~00 nini
V (mph)	68.6 63.3 57.3	386. 186. 186.	26.2 12.0 12.0	15.05 500.5 8.05 8.05	58.0 56.9 58.1	16.8 16.3 16.7	38.2			32.5
V _c (mph)	55.65	27.68 8 4.4.	25.03 5.04 6.04 6.04	1585 2567	55.55 6.56	1.65.1	24.6 2.6.0 2.6.0	0.99	5.15	31:1
Run	HUN		1-000		HUN					
Plight	ĸ		•		4					

TABLE II - Continued
ROTOR DRAG-LIFT RATIOS AND RELATED PARAMETERS
DERIVED FROM LEVEL-FLIGHT DATA

1-595

(i)	0.173 252 253	84. 75. 88.	.370 .253 .187	163	322	445	न्रमुद्	3.35.	.162 .166 .157	131.	72.55
(<u>1</u>)	900.00	985	.005 200 200 200 200	98.98 48.00	888 2523	<u>बुबु</u> ह	888	888	<u> इंड</u> ंड्	999	8999
Jd (1)	0.10t .075 .055	650 622 622 622 622	5.00 5.00 5.00 5.00 5.00 5.00 5.00 5.00	411.2	568 888	961. 101.	äää	1111	588	8.889 2893	हुंडुंडुं इंद्रुंड्ड
하다	0.281 .282	5.33	. 210 210 279	1883. 355.	25.95. 40.05.	262	. 262 262 270	. 272 . 267 . 273	268 268 165 165	262 263 263	. 25. 25. 25. 85.5.
કાક	0.0685 .0574 .0477	0511 0511 0483	0507 0547 0629	.0662 .0664 .0682	.0685 .0692 .0684	.0683 .0682 .0680	.0682 .0667 .0674	.0678 .0668 .0670	1990. 1990. 1990. 1990.	.0605 .0602 .0555	.0556 .0553 .0609 .0606
с _р × 103	0.352 .298 .266	484	.331 .331	& ES		2	£25.5	35.5. 35.5.5.	**************************************	202. 202. 772.	.276 .271 .318 .327
30 202	0.0298	.0299 .0299 .0294	.0500 .0293 .0506	.0262 .0269 .0365	.0366 .0370 .0346	.0345 .0320 .0327	.0325 .0300 .0296	.0294 .0280 .0273	.050. 1050. 10550.	.0290 .0286 .0290	.0288 .0284 .0304 .0313
<u>ያ</u>	0.0051 .0052 .0052		.0052 .0051 .0053	.001.5 .006.5 .006.3	888 848	.0059 .0055 .0056	.0056 .0051	.0051 .0048	.0052 4500. 0057	.0050 .0049 .0050	9659
비	5.1.5 9.1.5 9.1.5	8.47 14.67 12.75	5.53	38.7 2.8.5	388	2.2.R	2.16 2.95 2.95	22.2	85.4	5.5.5 4.5.5.	ディング ディング・ディング
CL	0.182 .250 .355	.508 .886 .776		170	196	196	.190 .172 .771	.176 .166 .167	198 195	230	125 205 205 205 205
4CL	7000	200.00		868 868 868	999 200 200 200 200	999	900.	900.	9000	999 988	9999
a f	6.65 6.6-10	12.6	-11.2 -8.9 -9.5	-10.7	10.7 10.5 10.3	-10.5	-11.6	-11.6	-11.8 -10.8	10.9	10.9
7 0₹	4. <i>i.</i> i.i.	-7.2 -12.5 -11.0	3.50	44.0 44.0	3.4.5	444	0.00 1.00 1.00 1.00 1.00 1.00 1.00 1.00	4.6.6	46.6	444 8084	2424 0000
(CL) uncor	0.177 245 361		. 233 . 212	.165 .167 .183	191.	181:	186.	021: 091: 191:	178	eigi Ž	9555 955 955 955 955 955 955 955 955 95
3.	0.238 .204 .166	걸음크	17.52	25.25	822		त्रंत्र	34.5	• • •		
9	10.3 8.1.5	7.5	888	9.6 12.7 2.2	12.2 12.2 1.7	7.11	201	922	10.5	9.99	0.000
(qdm)	505 51.7	35.50	8 K.88	75.0	72.7		787		72.72 4.76	22.7	82880 2444
V _c (mph)	71.5 60.5 19.2	32.2	36.4 51.4 5.1.4	127. 14.8	1.27	70.17	427			688	
E E	125	-\$100	စ ၈ ၀	125	440	1 −00 0	823	1 242	, 275	520	ಇಬ್ ತಬ
Flight	5			6							

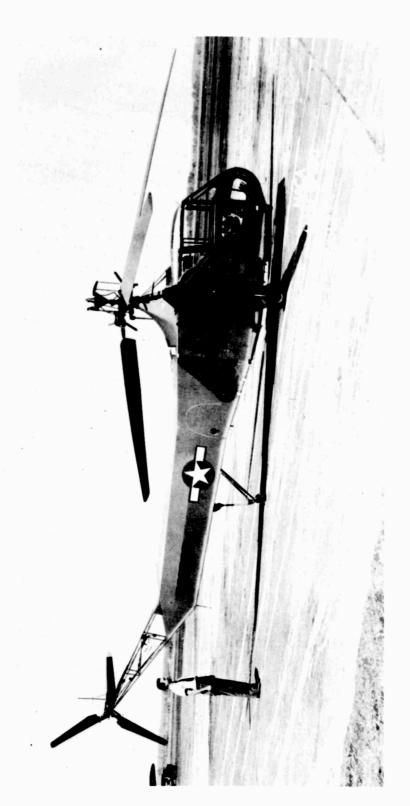


Figure 1.- HNS-1 helicopter, side view.

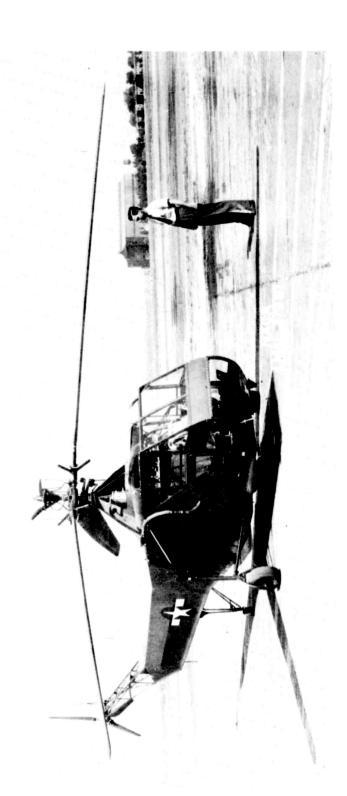


Figure 2.- HNS-1 helicopter, front three-quarter view.

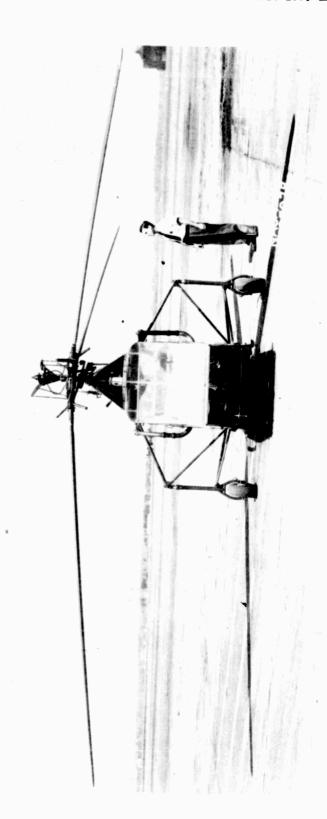


Figure 3.- HNS-1 helicopter, front view.

scale : 1" = 24"

L-595

Figure 4.- Planform dimensions of YR-4B main- and tail-rotor blades.



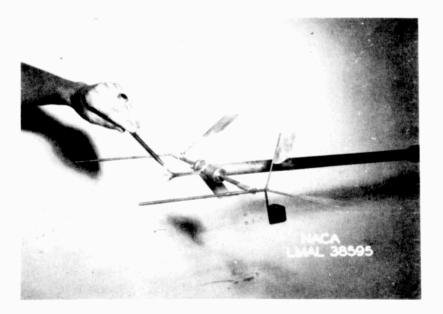
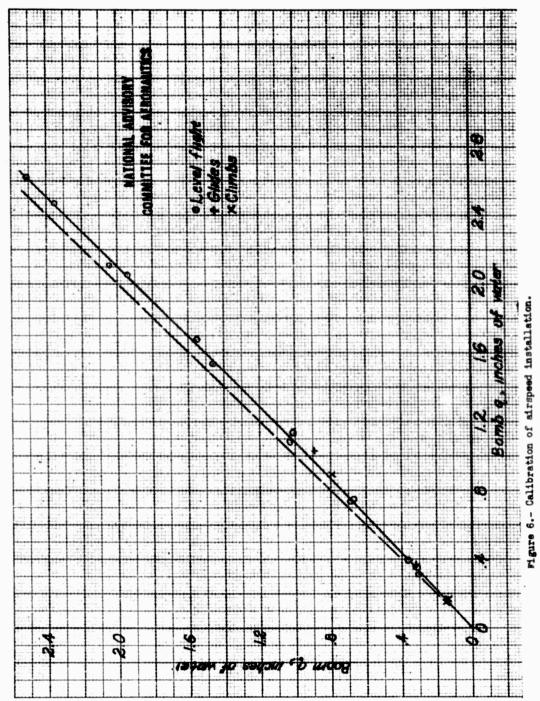


Figure 5.- Airspeed boom and details of pitot-static and flow-angle pressure-tube installations.



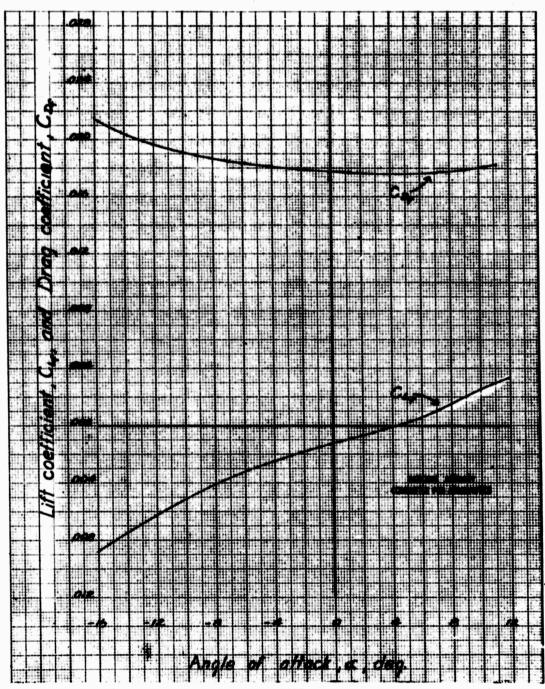
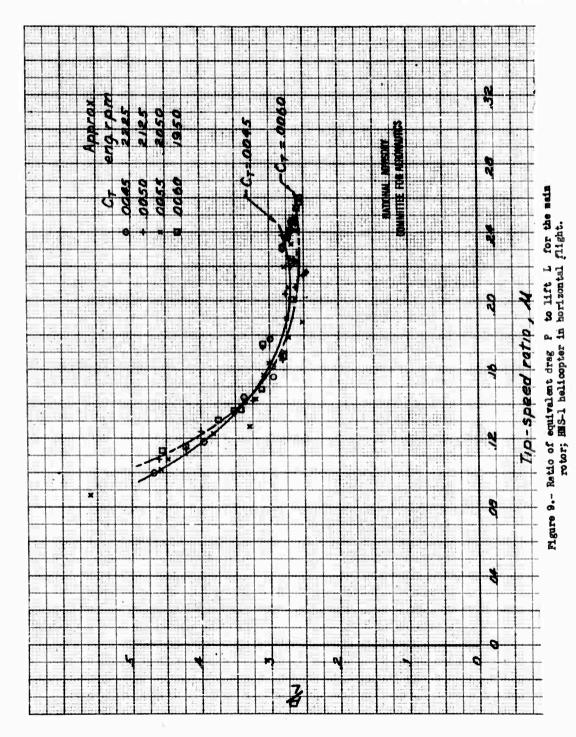


Figure 7.- Fuselage drag and lift curves as used in reduction of data;

Figure 8.- Main rotor shaft power vs. true speed for HNS-1 helicopter in level flight. Gross weight as flown, 2560 pounds ± 2 percent; density ratio e^{i}/e_{o} , .924 il.5 percent.



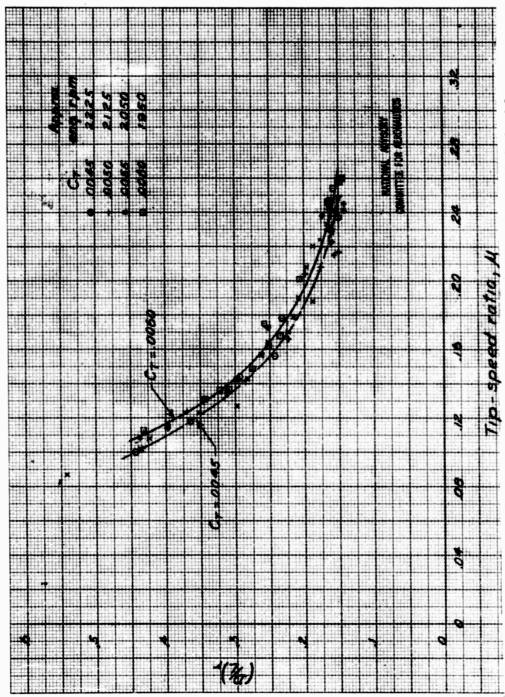


Figure 10.- Drag-lift ratio $(L/L)_r$ for the main rotor of the HNS-1 helicopter in horizontal flight. The drag of the hub structure and the cylindrical blade shanks has been charged to fuselage parasite values.

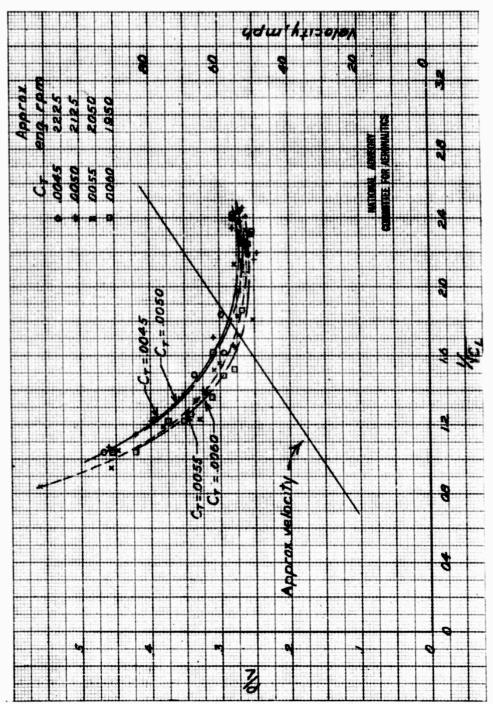


Figure 11.- Equivalent meda retor drag-lift ratio, P/L, vs. the valedity paremeter 1//01; MBS-1 helicopter in herizontal flight.

- 595

Figure 12.- Tail-rotor shaft power vs. true speed for the HNS-1 helicopter in horizontal flight.

Flight Tests of the Sikorsky HNS-1 (Army YR-4B) Helicopter - I - Experimental Data on Level-Flight Performance with Original Roser Blades
Gustafson, F. B.

33410 (None)

Langley Memorial Aeronautical Lab., Langley Field, Va. National Advisory Committee for Aeronautics, Washington, D. C. MR-L51

(Same)

March 145

Unclass.

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photos, tables, diagr, graphs

Level flight performance measurements were made on the YR-4B helicopter with the original set of main-rotor blades and a gross weight of approximately 2560 pounds. The minimum shaft power required by the main rotor at cruising rpm (225 rotor rpm, 2100 engine rpm) was approximately 99 hp at a speed of 40 mph. The shaft power absorbed by the tail rotor at cruising rpm was approximately 3 to 4 hp over a range of speeds from 25 to 80 mph.

Request copies of this report only from Originating Agency

Rotating Wing Aircraft (34)

Helicopters - Performance (49244);

YH-4B - Flight tests (99854.473)

AND, W. 188 NO. BC-1468 F